

## Answer on Question #61896 – Math – Linear Algebra

### Question

Let  $(x_1, x_2, x_3)$  and  $(y_1, y_2, y_3)$  represent the coordinates with respect to the bases

$$B_1 = \{(1,0,0), (0,1,0), (0,0,1)\}, B_2 = \{(1,0,0), (0,1,2), (0,2,1)\}.$$

If  $Q(X) = 2x_2x_1 + 2x_1x_2 - 2x_2x_3 + x_2x_2 + x_3x_3$ , find the representation of  $Q$  in terms of  $(y_1, y_2, y_3)$ .

### Solution

Given bases:

$$B_1: \begin{cases} x_1 = \langle 1; 0; 0 \rangle \\ x_2 = \langle 0; 1; 0 \rangle \\ x_3 = \langle 0; 0; 1 \rangle \end{cases}$$

$$B_2: \begin{cases} y_1 = \langle 1; 0; 0 \rangle \\ y_2 = \langle 0; 1; 2 \rangle \\ y_3 = \langle 0; 2; 1 \rangle \end{cases}$$

and the following polynomial:

$$Q(x) = 2x_1^2 + 2x_1x_2 - 2x_2x_3 + x_2^2 + x_3^2, \quad (1)$$

let's express variable "x" in terms of "y":

$$\begin{aligned} \begin{cases} y_1 = x_1 \\ y_2 = x_2 + 2x_3 \\ y_3 = 2x_2 + x_3 \end{cases} &\xrightarrow{R_2 \leftarrow R_2 - 2R_3} \begin{cases} y_1 = x_1 \\ y_2 - 2y_3 = -3x_2 \\ y_3 = 2x_2 + x_3 \end{cases} \xrightarrow{R_2 \leftarrow R_2 \div (-3)} \begin{cases} x_1 = y_1 \\ x_2 = \frac{2}{3}y_3 - \frac{1}{3}y_2 \\ 2x_2 + x_3 = y_3 \end{cases} \\ &\xrightarrow{R_3 \leftarrow R_3 - 2R_2} \begin{cases} x_1 = y_1 \\ x_2 = \frac{2}{3}y_3 - \frac{1}{3}y_2 \\ x_3 = y_3 - \frac{4}{3}y_3 + \frac{2}{3}y_2 \end{cases} \Rightarrow \begin{cases} x_1 = y_1 \\ x_2 = \frac{2}{3}y_3 - \frac{1}{3}y_2 \\ x_3 = \frac{2}{3}y_2 - \frac{1}{3}y_3 \end{cases} \end{aligned} \quad (2)$$

### Method 1

Substituting expressions for  $x_1, x_2, x_3$  from (2) into (1)

$$\begin{aligned} Q(x) &= 2x_1^2 + 2x_1x_2 - 2x_2x_3 + x_2^2 + x_3^2 = 2x_1^2 + 2x_1x_2 + (x_2 - x_3)^2 = \\ &= 2y_1^2 + 2y_1 \left( \frac{2}{3}y_3 - \frac{1}{3}y_2 \right) + \left( \frac{2}{3}y_3 - \frac{1}{3}y_2 - \frac{2}{3}y_2 + \frac{1}{3}y_3 \right)^2 = 2y_1^2 + \frac{4}{3}y_1y_3 - \frac{2}{3}y_1y_2 + (y_3 - y_2)^2 = \\ &= 2y_1^2 + \frac{4}{3}y_1y_3 - \frac{2}{3}y_1y_2 + y_2^2 - 2y_2y_3 + y_3^2. \end{aligned}$$

### Method 2

It follows from (2) that

$$x = Uy, \quad (3)$$

where  $x = \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix}$ ,  $U = \begin{pmatrix} 1 & 0 & 0 \\ 0 & -\frac{1}{3} & \frac{2}{3} \\ 0 & \frac{2}{3} & -\frac{1}{3} \end{pmatrix}$ ,  $y = \begin{pmatrix} y_1 \\ y_2 \\ y_3 \end{pmatrix}$ .

It follows from (1) that

$$Q(x) = x^T Ax = (x_1 \ x_2 \ x_3) \begin{pmatrix} 2 & 1 & 0 \\ 1 & 1 & -1 \\ 0 & -1 & 1 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix}, \quad (4)$$

where  $x = \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix}$ ,  $A = \begin{pmatrix} 2 & 1 & 0 \\ 1 & 1 & -1 \\ 0 & -1 & 1 \end{pmatrix}$ .

Rewrite (4) using (3)

$$Q(x) = x^T Ax = (Uy)^T A(Uy) = y^T U^T A U y = y^T (U^T A U) y = y^T C y, \quad (5)$$

hence

$$\begin{aligned} C &= U^T A U = \begin{pmatrix} 1 & 0 & 0 \\ 0 & -\frac{1}{3} & \frac{2}{3} \\ 0 & \frac{2}{3} & -\frac{1}{3} \end{pmatrix}^T \begin{pmatrix} 2 & 1 & 0 \\ 1 & 1 & -1 \\ 0 & -1 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 & 0 \\ 0 & -\frac{1}{3} & \frac{2}{3} \\ 0 & \frac{2}{3} & -\frac{1}{3} \end{pmatrix} = \\ &= \begin{pmatrix} 1 & 0 & 0 \\ 0 & -\frac{1}{3} & \frac{2}{3} \\ 0 & \frac{2}{3} & -\frac{1}{3} \end{pmatrix} \begin{pmatrix} 2 & 1 & 0 \\ 1 & 1 & -1 \\ 0 & -1 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 & 0 \\ 0 & -\frac{1}{3} & \frac{2}{3} \\ 0 & \frac{2}{3} & -\frac{1}{3} \end{pmatrix} = \begin{pmatrix} 2 & 1 & 0 \\ -\frac{1}{3} & -1 & 1 \\ \frac{2}{3} & 1 & -1 \end{pmatrix} \begin{pmatrix} 1 & 0 & 0 \\ 0 & -\frac{1}{3} & \frac{2}{3} \\ 0 & \frac{2}{3} & -\frac{1}{3} \end{pmatrix} = \\ &= \begin{pmatrix} 2 & -1/3 & 2/3 \\ -1/3 & 1 & -1 \\ 2/3 & -1 & 1 \end{pmatrix} \quad (6) \end{aligned}$$

Substituting the expression for the matrix  $C$  from (6) into (5)

$$\begin{aligned} Q(x) &= y^T C y = (y_1 \ y_2 \ y_3) \begin{pmatrix} 2 & -\frac{1}{3} & \frac{2}{3} \\ -\frac{1}{3} & 1 & -1 \\ \frac{2}{3} & -1 & 1 \end{pmatrix} \begin{pmatrix} y_1 \\ y_2 \\ y_3 \end{pmatrix} = \\ &= \left( 2y_1 - \frac{1}{3}y_2 + \frac{2}{3}y_3 \quad -\frac{1}{3}y_1 + y_2 - y_3 \quad \frac{2}{3}y_1 - y_2 + y_3 \right) \begin{pmatrix} y_1 \\ y_2 \\ y_3 \end{pmatrix} = \\ &= 2y_1^2 - \frac{1}{3}y_1y_2 + \frac{2}{3}y_1y_3 - \frac{1}{3}y_1y_2 + y_2^2 - y_2y_3 + \frac{2}{3}y_1y_3 - y_2y_3 + y_3^2 = \\ &= 2y_1^2 - \frac{2}{3}y_1y_2 + \frac{4}{3}y_1y_3 - 2y_2y_3 + y_2^2 + y_3^2 = \tilde{Q}(y). \end{aligned}$$

**Answer:**  $\tilde{Q}(y) = 2y_1^2 - \frac{2}{3}y_1y_2 + \frac{4}{3}y_1y_3 - 2y_2y_3 + y_2^2 + y_3^2$ .