Sample: Topology - Applied Topology

Task 1.

Give an explicit formula for a homeomorphism from a square to a circle in the Euclidean plane.

Proof. Let

$$S^1 = \{(x, y) \in \mathbf{R}^2 | x^2 + y^2 = 1\}$$

be the unit circle in \mathbf{R}^2 , and

$$Q = \partial([0,1] \times [0,1]) = \{(x,y) \in \mathbf{R}^2 | \max\{|x|, |y|\} = 1.$$

be the square with side 2 in the Euclidean plane centered at the origin, see Figure:



Define the map

 $f\colon Q\to S^1$

by the formula:

$$f(x,y) = \left(\frac{x}{\sqrt{x^2 + y^2}}, \frac{y}{\sqrt{x^2 + y^2}}\right).$$

Since

$$\left(\frac{x}{\sqrt{x^2+y^2}}\right)^2 + \left(\frac{y}{\sqrt{x^2+y^2}}\right)^2 = \frac{x^2+y^2}{x^2+y^2} = 1,$$

we see that $f(Q) \subset S^1$.

We claim that f is homeomorphism.

Geometrically, f acts as follows. Let $z \in Q$. Consider the straight segment [0, z] connecting the origin 0 = (0,0) with the point z. This segment intersect S^1 at a unique point, and this point is denoted by f(z), see Figure above.

To show that f is a homeomorphism it suffices to show that f is a continuous bijection whose inverse is also continuous.

1) f is continuous. Notice that the same formula for f defines the map

F

$$: \mathbf{R}^2 \setminus 0 \to S^1$$

by the formula:

$$F(x,y) = \left(\frac{x}{\sqrt{x^2 + y^2}}, \frac{y}{\sqrt{x^2 + y^2}}\right).$$

This map is continuous, since $\sqrt{x^2 + y^2} \neq 0$ for all $(x, y) \neq (0,0)$. But f is the restriction of F onto Q, and so f is continuous.

2) f is a bijection. For $z = (x, y) \neq 0$ let $R_z = \{tz = (tx, ty) \in \mathbf{R}^2 | t > 0\}$ be the open ray starting at the origin and passing through z.

Lemma. For any $z \neq 0$, each of the following intersections $R_z \cap Q, R_z \cap S^1$

consists of a unique point.

This lemma implies that f is a bijection. Indeed, first notice that if $z \in Q$, then

$$z=R_z\cap Q,$$

and by geometrical description of f

$$\begin{split} f(z) &= R_z \cap S^1.\\ \text{Now if } z_1 \neq z_2 \in Q, \text{ then the rays } R_{z_1} \cap R_{z_2} = \emptyset, \text{ and so}\\ f(z_1) &= R_{z_1} \cap S^1 \neq R_{z_2} \cap S^1 \neq f(z_2). \end{split}$$

Thus **f** is injective.

Moreover, let $p \in S^1$ and

$$z=R_p\cap Q,$$

then p = f(z), and so **f** is surjective.

Proof of Lemma. Suppose $z_1 = (x_1, y_1)$, $z_2 = (x_2, y_2) \in R_z \cap S^1$. Then $x_1^2 + y_1^2 = x_2^2 + y_2^2 = 1$,

and

$$z_1 = (x_1, y_1) = t_1 z_1 = (t_1 x, t_1 y), z_2 = (x_2, y_2) = t_2 z_2 = (t_2 x, t_2 y),$$

that is

$$x_1 = t_1 x, y_1 = t_1 y, x_2 = t_2 x, y_2 = t_2 y.$$

Then for
$$i = 1,2$$

$$x_i^2 + y_i^2 = t_i^2 x^2 + t_i^2 y^2 = t_i^2 (x^2 + y^2) = 1,$$

so

 $t_1^2(x^2+y^2)=t_2^2(x^2+y^2)=1.$ Since $z \neq 0$, we have that $x^2+y^2 \neq 0$, and so $t_1^2=t_2^2.$

But $t_1, t_2 > 0$, whence

$$t_1 = t_2$$
,

and thus $z_1 = z_2$. Similarly, suppose $z_1 = (x_1, y_1), z_2 = (x_2, y_2) \in R_z \cap Q$. Thus

$$\max\{|x_1|, |y_1|\} = \max\{|x_2|, |y_2|\} = 1$$

and

$$z_1 = (x_1, y_1) = t_1 z_1 = (t_1 x, t_1 y), z_2 = (x_2, y_2) = t_2 z_2 = (t_2 x, t_2 y),$$

that is

$$x_1 = t_1 x, y_1 = t_1 y, x_2 = t_2 x, y_2 = t_2 y.$$

Then for i = 1,2 $\max\{|x_i|, |y_i|\} = \max\{|t_ix|, |t_i, y|\} = t_i \max\{|x|, |y|\} = 1,$ since $t_i > 0$. Thus $t_1 \max\{|x|, |y|\} = t_2 \max\{|x|, |y|\} = 1.$ As $z \neq 0$, we have that $\max\{|x|, |y|\} > 0$, whence $t_1 = t_2,$ and thus $z_1 = z_2$. Lemma is proved.

3) f^{-1} is continuous. By 1) and 2) f is a continuous bijection. Since Q is compact, and S^1 is Hausdorff, it follows that the inverse of f is also continuous, and so f is a homeomorphism.

Task 2.

Let $D^{\circ} = \{(x, y) \in \mathbf{R}^2 : x^2 + y^2 < 1\}$ be the open disk.

(a) Let $f: D^{\circ} \to \mathbf{R}^{3}$ be defined by $f((r, \theta)) = (r, \theta, r)$ where (r, θ) and (r, θ, r) are in polar and cylindrical coordinates, respectively. Show that f is an embedding of D° and describe the embedded copy $f(D^{\circ})$ in \mathbf{R}^{3} .

(b) Describe the stereographic projection in \mathbf{R}^3 of $f(D^\circ)$ onto the plane z = 0 from a light source located at the point (0,0,1). Is this a homeomorphism? Find an explicit formula for this stereographic projection function p.

(c) Describe all planes in \mathbb{R}^3 for which stereographic projection of $f(D^\circ)$ from a light source at (0,0,1) is a homeomorphism.

Solution.

(a) Notice that in Cartesian coordinates (x, y) we have that $r = \sqrt{x^2 + y^2}$. Then the map $f: D^\circ \to \mathbf{R}^3$

$$f((r,\theta)) = (r,\theta,r)$$

in coordinates (x, y) is given by the formula:

$$f(x, y) = (x, y, \sqrt{x^2 + y^2}).$$

This formula shows that f f is continuous.

Moreover **f** is injective, since for $(r, \theta) \neq (r', \theta') \in D^\circ$, we have that $f((r, \theta)) = (r, \theta, r) \neq (r', \theta', r') = f((r, \theta)).$

Also consider the map $p: \mathbf{R}^2 \to \mathbf{R}^3$ defined by p(x, y, z) = (x, y). Then

$$p \circ f(x, y) = p(x, y, \sqrt{x^2 + y^2}) = (x, y)$$

and so the restriction of p onto $f(D^{\circ})$ is the inverse to f. This proves that f is an embedding, i.e. a homeomorphism onto its image.

Notice $f(D^{\circ})$ is the graph of the function $g(x, y) = \sqrt{x^2 + y^2}$, and so it is the open cone over the circle

$${x^2 + y^2 = 1, z = 1}$$

and vertex at the origin



(b) Let us find formula for stereographic projection π from the point N = (0,0,1). This maps associates to each point $A(x, y, z) \in \mathbf{R}^3$ the intersection point of the ray NA with the plane $\{z = 0\}$. In particular, this map is defined only for points A with z < 1, i.e on the open half-space

$$X = \{(x, y, z) | z < 1\}.$$

Notice that this projection preserves θ , that is $\theta(A) = \theta(\pi(A))$. Consider the figure:



It follows from similarity of triangles ΔATN and $\pi(A)ON$ that $\frac{R}{r} = \frac{1}{1-r'}$

whence π is given by the formula

$$\pi(r,\theta,z) = \left(\frac{r}{1-z},\theta\right).$$

Then the composition $\pi \circ f: D^{\circ} \to \mathbf{R}^2$ is given by the formula

$$\pi \circ f(r,\theta) = \pi(r,\theta,r)\left(\frac{r}{1-r},\theta\right).$$

Notice that the function

$$y(r) = \frac{r}{1-r} = \frac{r-1+1}{1-r} = \frac{1}{1-r} - 1$$

is strictly monotone and maps the interval [0,1) onto $[0,+\infty)$. Its inverse is given by

$$y^{-1}(\rho) = 1 - \frac{1}{1+\rho} = \frac{1+\rho-1}{1+\rho} = \frac{\rho}{1+\rho} =$$

This implies that $\pi \circ f$ is a homeomorphism and its inverse is given by

$$(\pi \circ f)^{-1}(r,\theta) = \left(\frac{r}{1+r},\theta\right).$$

(c) Let *P* be a plane in \mathbb{R}^3 such that π is defined on *P*. As noted in 2) the stereographic projection $\pi: X \to \mathbb{R}^2$ is defined only for points (x, y, z) with z < 1, whence $P \subset X$. But this is possible only if *P* is given by the equation z = c, where c < 1.

We claim that for every such plane the restriction of π to P is a homeomorphism $P \to \mathbf{R}^2$. Let $(r, \phi, c) \in P$. Then

$$\pi(r,\theta,c) = \left(\frac{r}{1-c},\theta\right).$$

Therefore in Cartesian coordinates we have that

$$\pi(x, y, c) = \left(\frac{x}{1-c}, \frac{y}{1-c}\right),$$

that is the restriction $\pi|_P$ of π to P is a homothety with coefficient $\frac{1}{1-c}$. Hence its inverse is a homothety with coefficient 1-c, and so $\pi|_P$ is a homeomorphism.



Are these sets open, closed, both, or neither in $\mathbf{R} \times \mathbf{R}$, $\mathbf{R}_l \times \mathbf{R}$, $\mathbf{R}_l \times \mathbf{R}_l$, where \mathbf{R}_l is the plane with lower limit topology?

Solution.

Recall that lower limit topology on R is generated by half-open intervals

$$\{[a, b) \subset \mathbf{R} | a < b\}.$$

The set **R** with this topology is denoted by \mathbf{R}_l .

Notice that every interval of the form (a, b) is open in \mathbf{R}_l , since

$$(a,b) = \bigcup_{i \ge 1} [a - 1/i, b]$$

Therefore every closed (resp. open) subset of **R** is also closed (resp. open) in \mathbf{R}_l , and so topology on \mathbf{R}_l is stronger than the usual topology on **R**.

This implies that the topology on $\mathbf{R}_l \times \mathbf{R}_l$ is stronger than the topology of $\mathbf{R}_l \times \mathbf{R}$, which in turn is stronger than topology on $\mathbf{R}^2 = \mathbf{R} \times \mathbf{R}$.

Also notice that topology on $\mathbf{R} imes \mathbf{R}$ is generated by sets of the form

$$\{(a,b) \times (c,d) | a < b, c < d\}$$

topology on $\mathbf{R}_l \times \mathbf{R}$ is generated by sets of the form

$$\{[a, b) \times (c, d) | a < b, c < d\},\$$

and topology on $\mathbf{R}_l \times \mathbf{R}_l$ is generated by sets of the form

 $\{[a,b) \times [c,d) | a < b, c < d\},\$





(a) The set in (a) is a closed 2-disk and can be defined by the formula:

$$A = \{ (x, y) \in \mathbf{R}^2 | x^2 + y^2 \le 1.$$

Let us show that A is **closed**. Let $\{(x_i, y_i)\}_{i \ge 1} \subset A$ be a sequence of points converging to some $(x, y) \in \mathbf{R}^2$. Then

$$x^2 + y^2 = \lim_{i \to \infty} x_i^2 + y_i^2 \le 1,$$

whence $(x, y) \in A$, and so A is closed.

Therefore *A* is also closed in $\mathbf{R}_l \times \mathbf{R}$, $\mathbf{R}_l \times \mathbf{R}_l$.

On the other hand, **A** is not open in neither of $\mathbf{R} \times \mathbf{R}$, $\mathbf{R}_l \times \mathbf{R}$, $\mathbf{R}_l \times \mathbf{R}_l$.

Since $\mathbf{R}_l \times \mathbf{R}_l$ has the strongest topology, it suffices to prove that A is not open in $\mathbf{R}_l \times \mathbf{R}_l$. Consider the point $z = (1,0) \in A$ and let $U = [a,b) \times [c,d)$ be any neighborhood of z in $\mathbf{R}_l \times \mathbf{R}_l$, so $a \le 1 < b$ and $c \le 0 < d$. Take any $q \in (1,b)$. Then the point $(q,0) \in U$, but $q \not\in A$. Thus $U \not\subset A$, and so A is not open in $\mathbf{R}_l \times \mathbf{R}_l$. Therefore it is not open in $\mathbf{R} \times \mathbf{R}$, $\mathbf{R}_l \times \mathbf{R}_l$.

(b) The set in (b) can be given by the formula:

 $B = \{(x, y) \in \mathbb{R}^2 | |x| + |y| \le 1\} \setminus \{(x, y) | |x| + |y| = 1 \text{ and } y > 0\}.$ This set is neither open nor closed in any of topologies of $\mathbb{R} \times \mathbb{R}$, $\mathbb{R}_l \times \mathbb{R}$, $\mathbb{R}_l \times \mathbb{R}_l$. Again it suffices to show this for $\mathbb{R}_l \times \mathbb{R}_l$.

Let us show that *B* is not open in $\mathbf{R}_l \times \mathbf{R}_l$. Consider the point $(-1,0) \in B$ and let $U = [a,b) \times [c,d)$ be any neighborhood of *z* in $\mathbf{R}_l \times \mathbf{R}_l$, so $a \leq -1 < b$ and $c \leq 0 < d$. Take any $q \in (0,d)$. Then the point $(-1,q) \in U$, but $q \notin B$, since

$$|-1| + |q| > 1.$$

Thus $U \not\subseteq B$, and so B is not open in $\mathbf{R}_l \times \mathbf{R}_l$. Therefore it is not open in $\mathbf{R} \times \mathbf{R}$, $\mathbf{R}_l \times \mathbf{R}_l$. Let us show that B is not closed in $\mathbf{R}_l \times \mathbf{R}_l$. For this it suffices to show that $\mathbf{R}_l \times \mathbf{R}_l \setminus B$ is not open. Again consider the point $(0.5, -0.5) \in B$ and let $U = [a, b) \times [c, d)$ be any neighborhood of z in $\mathbf{R}_l \times \mathbf{R}_l$, so $a \le 0.5 < b$ and $c \le -0.5 < d$. Take any $q \in (0.5, b)$. Then the point $(q, -0.5) \in U$, but $q \not\in B$, since

|q| + |-0.5| > |0.5| + |-0.5| = 1.

Thus $U \not \subset \mathbf{R}_l \times \mathbf{R}_l \setminus B$, and so $\mathbf{R}_l \times \mathbf{R}_l \setminus B$ is not open in $\mathbf{R}_l \times \mathbf{R}_l$, whence *B* is not closed in $\mathbf{R}_l \times \mathbf{R}_l$. Therefore it is not open in $\mathbf{R} \times \mathbf{R}$, $\mathbf{R}_l \times \mathbf{R}$ as well.

(c) The set in (c) can be given by the formula:

 $C = \{(x, y) \in \mathbb{R}^2 | |x| + |y| < 1\} \cup \{(x, y) | |x| + |y| = 1 \text{ and } x + y = -1\}.$ We claim that this set is also neither open nor closed in any of topologies of $\mathbb{R} \times \mathbb{R}$, $\mathbb{R}_l \times \mathbb{R}$, $\mathbb{R}_l \times \mathbb{R}_l$.

Again it suffices to show this for $\mathbf{R}_l \times \mathbf{R}_l$.

Let us show that *C* is not open in $\mathbf{R}_l \times \mathbf{R}_l$. Consider the point $(-1,0) \in C$ and let $U = [a,b) \times [c,d)$ be any neighborhood of *z* in $\mathbf{R}_l \times \mathbf{R}_l$, so $a \leq -1 < b$ and $c \leq 0 < d$. Take any $q \in (0,d)$. Then the point $(-1,q) \in U$, but $q \notin C$, since

$$|-1|+|q|>1.$$

Thus $U \not\subset C$, and so C is not open in $\mathbf{R}_l \times \mathbf{R}_l$. Therefore it is not open in $\mathbf{R} \times \mathbf{R}$, $\mathbf{R}_l \times \mathbf{R}$. Let us show that C is not closed in $\mathbf{R}_l \times \mathbf{R}_l$. For this it suffices to show that $\mathbf{R}_l \times \mathbf{R}_l \setminus C$ is not open. Again consider the point $(0.5, -0.5) \in C$ and let $U = [a, b) \times [c, d)$ be any neighborhood of z in $\mathbf{R}_l \times \mathbf{R}_l$, so $a \le 0.5 < b$ and $c \le -0.5 < d$. Take any $q \in (0.5, b)$. Then the point $(q, -0.5) \in U$, but $q \not\in C$, since

$$q| + | -0.5| > |0.5| + | -0.5| = 1.$$

Thus $U \not \subset \mathbf{R}_l \times \mathbf{R}_l \setminus C$, and so $\mathbf{R}_l \times \mathbf{R}_l \setminus C$ is not open in $\mathbf{R}_l \times \mathbf{R}_l$, whence *C* is not closed in $\mathbf{R}_l \times \mathbf{R}_l$. Therefore it is not open in $\mathbf{R} \times \mathbf{R}$, $\mathbf{R}_l \times \mathbf{R}$ as well.

Answer. In the case (a) the set A is closed in each spaces $\mathbf{R} \times \mathbf{R}$, $\mathbf{R}_l \times \mathbf{R}$, $\mathbf{R}_l \times \mathbf{R}_l$ but not open in neither of the spaces.

In the cases (b) and (c) the corresponding sets are neither open nor closed in any of the spaces $\mathbf{R} \times \mathbf{R}$, $\mathbf{R}_l \times \mathbf{R}$, $\mathbf{R}_l \times \mathbf{R}_l$.